# CALCULATION OF THE CAVITATING FLOW AROUND A CIRCULAR CONE BY A SUBSONIC STREAM OF A COMPRESSIBLE FLUID $\dagger$ 

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#### Abstract

The problem of the flow around a circular cone according to the Ryabushinskii scheme by an axially symmetric subsonic compressible fluid is considered in a non-linear formulation. A numericalanalytical method is proposed for solving the problem, based on the use of the variables of a velocity hodograph, and is a development of the method proposed [1] for calculating the jet efflux from a funnel-shaped vessel. Results of a numerical investigation of the cavitating flow around a disc and cavitator with a conical channel by an axially symmetric subsonic stream of water are presented.


Problems of the axially symmetric cavitating flow of an incompressible fluid have been solved numerically in a non-linear formulation in many papers. Cavitators in the form of a sphere, a disc and a right circular cone were considered. The most important results which follow from an investigation of the cavitating flow around a disc and a cone by an incompressible fluid were obtained in $[2,3]$. The results in $[4,5]$ are in good agreement with them.

Axially symmetric cavitating flows of a compressible fluid with a non-zero cavitation number $Q$ have only been investigated previously in a linear formulation using thin-body gas dynamic methods [6-11].

1. Consider the axially symmetric subsonic flow around a circular cone by a compressible fluid according to the Ryabushinskii scheme. We assume that the fluid is ideal and weightless and that the flow is steady, irrotational and isentropic. In the plane of the cylindrical coordinates $x, r$, the domain occupied by the flow is bounded by the segments $A B$ and $H A$ of the axis of symmetry $x$, by the generatrices of the cones $B C$ and $H G$ which make an angle $\theta_{0}$ with the axis of symmetry and by the arc $C D G$ of the free surface (Fig. 1a). The origin of coordinates is chosen so that the plane $x=0$ serves as a plane of symmetry of the flow (the half-line $D A$ belongs to this plane).

Let $\lambda$ be the reduced velocity, $M$ the Mach number, $\theta$ the angle of inclination of the velocity to the $x$-axis $\left(\theta=0\right.$ on $A B, H A$ and $D A$ ) and $\lambda_{a}$ and $\lambda_{c}$ the values of $\lambda$ at an infinitely distant point $A$ and in $C D G$, respectively $\left(\lambda_{a}<\lambda_{c} \leqslant 1\right), \tau=\lambda / \lambda_{a}, \tau_{0}=\lambda_{c} / \lambda_{a}$. In the ( $\tau, \theta$ )-plane, the parts of the flow domain lying to the left of the plane $x=0$ correspond to the rectangle

$$
\Sigma_{0}=\left\{(\tau, \theta) \mid 0<\tau<\tau_{0}, 0<\theta<\theta_{0}\right\}
$$

(Fig. 1b; the segment $B B_{1}$ corresponds to the stagnation point $B$ ).
Introducing the velocity potential $\varphi$ and the stream function $\psi$ by means of the relationships


Fig. 1.

$$
\tau \cos \theta=\varphi_{x}=(r v)^{-1} \psi_{r}, \quad \tau \sin \theta=\varphi_{r}=-(r v)^{-1} \Psi_{x}, \quad v=\rho / \rho_{0}
$$

and putting $z=x+i r$, we write

$$
\begin{equation*}
d z=\tau^{-1}\left[d \varphi+i(r \nu)^{-1} d \psi\right] e^{i \theta} \tag{1.1}
\end{equation*}
$$

By treating $\tau$ and $\theta$ as the independent variables, we obtain from (1.1)

$$
\begin{equation*}
x_{\mathrm{K}}+i r_{\mathrm{\kappa}}=\tau^{-1}\left[\varphi_{\mathrm{K}}+i(r v)^{-1} \Psi_{\mathrm{\kappa}}\right] e^{i \theta}, \quad \kappa=\tau, \theta \tag{1.2}
\end{equation*}
$$

By cross differentiation of (1.2), we find

$$
\begin{gather*}
\varphi_{\theta}=\tau(r v)^{-1} \psi_{\tau}  \tag{1.3}\\
\varphi_{\tau}=\left[\frac{\partial}{\partial \tau}\left(\frac{1}{r v}\right)-\frac{1}{r v \tau}\right] \psi_{\theta}-\frac{1}{v} \frac{\partial}{\partial \theta}\left(\frac{1}{r}\right) \psi_{\tau} \tag{1.4}
\end{gather*}
$$

Using Euler's equation $\rho V d V+d p=0$ and the relationship $d p / d \rho=a^{2}$ ( $V$ is the modulus of the velocity and $a$ is the velocity of sound), we reduce (1.4) to the form

$$
\begin{gather*}
\varphi_{\tau}=(r v \tau)^{-1}\left(M^{2}-1\right) \psi_{\theta}+(r v \tau \sin \theta)^{-1} F  \tag{1.5}\\
F=\tau r^{-1}\left(\psi_{\tau} r_{\theta}-\psi_{\theta} r_{\tau}\right) \sin \theta \tag{1.6}
\end{gather*}
$$

Using (1.3) and (1.5), we obtain from (1.2)

$$
\begin{align*}
& r x_{\tau}=\left[\left(M^{2}-1\right) \psi_{\theta} \cos \theta+F \operatorname{ctg} \theta-\tau \psi_{\tau} \sin \theta\right]\left(\nu \tau^{2}\right)^{-1} \\
& r x_{\theta}=\left[\tau \psi_{\tau} \cos \theta-\psi_{\theta} \sin \theta\right](\nu \tau)^{-1}  \tag{1.7}\\
& y_{\tau}=G=\left[\left(M^{2}-1\right) \psi_{\theta} \sin \theta+F+\tau \psi_{\tau} \cos \theta\right]\left(\nu \tau^{2}\right)^{-1} \\
& y_{\theta}=H=\left[\tau \psi_{\tau} \sin \theta+\psi_{\theta} \cos \theta\right](\nu \tau)^{-1}, \quad y=r^{2} / 2 \tag{1.8}
\end{align*}
$$

From (1.6) and (1.8), we find

$$
\begin{equation*}
F=\sin ^{2} \theta\left[\tau^{2} \psi_{\tau}^{2}+\left(1-M^{2}\right) \psi_{\theta}^{2}\right]\left(2 Y+\psi_{\theta} \sin \theta\right)^{-1}, \quad Y=\nu \tau y \tag{1.9}
\end{equation*}
$$

Eliminating $\varphi$ from (1.3) and (1.5), we arrive at the equation

$$
\begin{align*}
& L(\Psi)=N(\psi, Y), \quad N(\Psi, Y)=\frac{1}{\sin \theta} \frac{\partial F}{\partial \theta}  \tag{1.10}\\
& L(\Psi)=\left(1-M^{2}\right) \psi_{\theta \theta}+\tau^{2} \psi_{\tau \tau}+\left(1+M^{2}\right) \tau \psi_{\tau}
\end{align*}
$$

In deriving formulae (1.7)-(1.10) we have used the assumptions regarding the steady, barotropic, potential and adiabatic nature of the flow but no actual relationship between the gas dynamic parameters. Relationships (1.7)-(1.10) (which were first obtained in [1]) are therefore applicable to the investigation of flows of compressible liquids and gases with different equations of state.
The following conditions must be satisfied on the boundary of the domain $\Sigma_{0}$

$$
\begin{equation*}
\psi=0 \text { on } A B B_{1} C D, \quad \psi_{\theta}=0 \text { on } A D, \quad y=0 \text { on } A B B_{1} \tag{1.11}
\end{equation*}
$$

Using (1.8), (1.9) and (1.11), $Y$ can be expressed in terms of $\psi$

$$
\begin{align*}
& Y=Y(\psi)=\psi \cos \theta+\int_{0}^{\theta}\left(\tau \psi_{\tau}+\psi\right) \sin \theta d \theta+\Omega(\psi)  \tag{1.12}\\
& \Omega(\psi)=\left.v \tau \int_{1}^{\tau}\left(v \tau^{2}\right)^{-1}\left(1-M^{2}\right) \psi\right|_{\theta=0} d \tau
\end{align*}
$$

Hence, the problem reduces to determining the function $\psi(\tau, \theta)$, which satisfies relationships (1.10), (1.9) and (1.12) in the domain $\Sigma_{0}$, with the boundary conditions (1.11) and

$$
\begin{equation*}
\psi>0, \quad(\tau, \theta) \in \Sigma_{0} \tag{1.13}
\end{equation*}
$$

On $C D$, we have $\psi_{\theta}=0$ and the following formulae for the curvature $K$ of the $\operatorname{arc} C D$ is therefore obtained from (1.7) and (1.8)

$$
\begin{equation*}
K=\left.\frac{x_{\theta} r_{\theta \theta}-r_{\theta} x_{\theta \theta}}{\left(x_{\theta}^{2}+r_{\theta}^{2}\right)^{3 / 2}}\right|_{\tau=\tau_{0}}=-\left.v r \psi_{\tau}^{-1}\right|_{\tau=\tau_{0}} \tag{1.14}
\end{equation*}
$$

Since $\psi_{\tau}=0$ on $B_{1} C$, it follows from (1.4) that $K \rightarrow \infty$ on approaching the point of contact of the free surface with the surface of the cone (this assertion has been proved in [12] in the case of an incompressible fluid).
2. Let us represent the solution of the problem in the form $\psi=\psi^{0}+\chi$, where $\psi^{0}$ is the singular part of $\psi$ which describes the behaviour of the stream function in the neighbourhood of point $A$ and determines the topology of the flow. The method of asymptotic expansions is used in the search for $\psi^{0}$.

Let us put

$$
\begin{equation*}
\omega=\operatorname{arctg} \frac{\theta}{\alpha \zeta}, \quad \zeta=\tau-1, \quad \alpha=\left(1-M_{a}^{2}\right)^{1 / 2} \tag{2.1}
\end{equation*}
$$

Here, $M_{a}$ is the value of $M$ when $\lambda=\lambda_{a}$ and $\omega \in[0, \pi]$ when $(\tau, \theta) \in \Sigma_{0}$.
We shall seek the asymptotic expansion of the function $\psi^{0}=\psi^{0}(\theta, \omega)$ with respect to $\theta$, representing the principal term $\psi^{01}$ in the form $\psi^{01}=\theta^{-n} f_{1}(\omega)(n=$ const, $n>0)$. Here

$$
\begin{align*}
& \psi_{\tau}^{01}=-\alpha \theta^{-n-1} \sin ^{2} \omega f_{1}^{\prime}, \quad \psi_{\theta}^{01}=\theta^{-n-1}\left(-n f_{1}+1 / 2 \sin 2 \omega f_{1}^{\prime}\right) \\
& \psi_{\mathfrak{\pi}}^{01}=\alpha^{2} \theta^{-n-2}\left(2 \sin ^{3} \omega \cos \omega f_{1}^{\prime}+\sin ^{4} \omega f_{1}^{\prime \prime}\right)  \tag{2.2}\\
& \psi_{\theta \theta}^{01}=\theta^{-n-2}\left[n(n+1) f_{1}-\left(n+\sin ^{2} \omega\right) \sin 2 \omega f_{1}^{\prime}+1 / 4 \sin ^{2} 2 \omega f_{1}^{\prime \prime}\right]
\end{align*}
$$

In accordance with (1.11) and (1.13), we subject $\psi^{01}$ to the conditions

$$
\begin{equation*}
\psi_{\theta}^{01}=0, \omega=0 ; \quad \Psi^{01}=0, \omega=\pi ; \quad \psi^{01}>0, \quad 0 \leqslant \omega<\pi \tag{2.3}
\end{equation*}
$$

When account is taken of (2.1) and (2.2), we obtain from the first equality of (2.3) that

$$
\begin{equation*}
\omega^{-n-1}\left(-n f_{1}+\sin \omega f_{1}^{\prime}\right) \rightarrow 0, \quad f_{1}=O\left(\omega^{n}\right), \quad \Psi^{01}=O\left(\zeta^{-n}\right) \quad \text { as } \quad \omega \rightarrow 0 \tag{2.4}
\end{equation*}
$$

In expression (1.12), we put $\psi=\psi^{01}$ and change from the variables $\tau, \theta$ to the variables $\theta, \omega$ (since $\tau-1=\alpha^{-1} \theta \operatorname{ctg} \omega$, any analytic function $\tau$ can be represented in the form of a series in powers of $\theta$ with coefficients which depend on $\omega$ ). When account is taken of (2.1), (2.2) and (2.4), we shall have

$$
\begin{aligned}
& \Omega\left(\psi^{01}\right)=O\left(\zeta^{-n+1}\right)=O\left(\theta^{-n+1}\right), \quad \int_{0}^{\theta} \tau \psi_{\tau}^{01} \sin \theta d \theta=O\left(\theta^{-n+1}\right) \\
& \int_{0}^{\theta} \psi^{01} \sin \theta d \theta=O\left(\theta^{-n+2}\right), \quad Y\left(\psi^{01}\right)=\theta^{-n} f_{1}(\omega)+O\left(\theta^{-n+1}\right)
\end{aligned}
$$

In relation (1.10), we put $\psi=\psi^{01}$ and change to the variables $\theta, \omega$. On equating the principal terms in the expansions of the left- and right-hand sides of (1.10) in powers of $\theta$ (terms of the order of $\theta^{-n-2}$ ), we obtain a differential equation in $f_{1}(\omega)$ from which, after the substitution $f_{1}(\omega)=\sin ^{\pi} \omega \varphi_{1}(\omega)$ we obtain the equation

$$
\begin{align*}
& {\left[4+\left(n^{2}-4 n\right) \sin ^{2} \omega\right] \varphi_{1}^{2} \varphi_{1}^{\prime \prime}+\left[\left(4+2 n-n^{2}\right) \sin ^{2} \omega-4\right] \varphi_{1} \varphi_{1}^{\prime 2}+1 / 2 \sin 2 \omega\left(\varphi_{1}^{3}+n^{2} \varphi_{1}^{2} \varphi_{1}^{\prime}\right)+} \\
& +\left(4 n^{2}-2 n^{3}\right) \sin ^{2} \omega \varphi_{1}^{3}=0 \tag{2.5}
\end{align*}
$$

The conditions

$$
\begin{equation*}
\varphi_{1}^{\prime}(0)=0 ; \varphi_{1}(\pi)=0 ; \varphi_{1}(\omega)>0,0 \leqslant \omega<\pi \tag{2.6}
\end{equation*}
$$

are obtained from (2.3) for $\varphi_{1}(\omega)$.
Analysis shows that a unique solution (apart from a constant factor) of problem (2.5), (2.6) exists and that it holds when $n=2 / 3$. The required function $\varphi_{1}$ is found by numerical integration of (2.5) from the point $\omega=\pi-\varepsilon \quad(0<\varepsilon \ll 1)$ to $\omega=0$ taking account of the fact that the expansion

$$
\begin{equation*}
\varphi_{1}(\pi-t)=t^{2}-\frac{1}{3} t^{4}+\frac{28}{405} t^{6}-\frac{5129}{612360} t^{8}+\ldots \tag{2.7}
\end{equation*}
$$

holds in the neighbourhood of the point $\omega=\pi$.
In the neighbourhood of the point $\omega=0$

$$
\begin{equation*}
\varphi_{1}(\omega)=b\left(1-\frac{2}{81} \omega^{4}-\frac{4}{2187} \omega^{6}+\frac{91}{229635} \omega^{8}+\ldots\right) \tag{2.8}
\end{equation*}
$$

where $b=1.4174112$ (it is found by numerical integration). The function $\varphi_{1}(\omega)$ decreases monotonically from the value $b$ to zero in the interval $0 \leqslant \omega \leqslant \pi$ while $\varphi_{1}^{\prime}(\omega)$ vanishes at the ends of the interval and has a single minimum. A plot of the function $\varphi_{1}(\omega)$ is shown in Fig. 2, curve 1.

Hence, $\psi^{01}=\theta^{-2 / 3} \sin ^{2 / 3} \omega \varphi_{1}(\omega)=\mu^{-2 / 3} \varphi_{1}(\omega)$, where $\mu=\left(\sigma^{2}+\theta^{2}\right)^{1 / 2}, \sigma=\alpha(\tau-1)$. The quantities $\eta$ and $\omega$ serve as polar coordinates in the affinely transformed plane of the hodograph $\sigma, \theta$ and all curves $\psi^{01}=$ const are similar. On approaching the singular point from all directions $\omega=$ const, apart from $\omega=\pi, \psi^{01}$, tends to infinity as $\mu^{-2 / 3}$ (when $\omega=\pi \psi^{01}=0$ ).

A discrepancy of the order of $\theta^{-\frac{8}{3}}$ is obtained as the result of the substitution of $\psi^{01}$ into Eq. (1.10). It is natural to seek the term following $\psi^{01}$ in the expansion of $\psi^{0}(\theta, \omega)$ with respect to $\theta$ in the form $\psi^{02}=\theta^{y_{3} / 3} f_{2}(\omega)$ while requiring that a discrepancy of the order of $\theta^{-2 / 3}$


Fig. 2.
should be obtained as the result of substituting $\psi^{01}+\psi^{02}$ into (1.10).
By requiring that $\psi_{\theta}^{02}=0$ when $\omega=0$ and $\psi^{02}=0$ when $\omega=\pi$, we obtain the boundary conditions for $f_{2}(\omega)$

$$
\begin{equation*}
\lim _{\omega \rightarrow 0} \omega^{-2 / 3}\left(\frac{1}{3} f_{2}+\frac{1}{2} \sin 2 \omega f_{2}^{\prime}\right)=0, \quad \lim _{\omega \rightarrow \pi}(\pi-\omega)^{1 / 3} f_{2}=0 \tag{2.9}
\end{equation*}
$$

It follows from (2.9), in particular, that $f_{2}=O\left(\omega^{-1 / 3}\right), \psi^{02}=O\left(\xi^{1 / 3}\right)$ when $\omega \rightarrow 0$ and, hence, $\Omega\left(\psi^{02}\right)=O\left(\xi^{1 / 3}\right)=O\left(\theta^{1 / 3}\right)$. When account is taken of the last relationship of (2.2), we find

$$
\begin{align*}
& Y\left(\psi^{01}+\psi^{02}\right)=\theta^{-2 / 3} f_{1}(\omega)+\theta^{1 / 3} f_{2}(\omega)+\alpha \theta^{1 / 3} F_{1}(\omega)+O\left(\theta^{4 / 3}\right) \\
& F_{1}(\omega)=3 b(\operatorname{ctg} \omega)^{1 / 3}+F_{0}(\omega), \quad \omega \in[0, \pi / 2] \\
& F_{1}(\omega)=F_{0}(\omega), \quad \omega \in[\pi / 2, \pi]  \tag{2.10}\\
& F_{0}(\omega)=-\left(\operatorname{ctg}^{2} \omega\right)^{1 / 6} \int_{0}^{\omega}\left(\operatorname{tg}^{2} \omega\right)^{2 / 3} f_{1}^{\prime \prime}(\omega) d \omega, \quad \omega \in[0, \pi / 2) \\
& F_{0}(\omega)=\left(\operatorname{ctg}^{2} \omega\right)^{y / 6} \int_{\pi}^{\omega}\left(\operatorname{tg}^{2} \omega\right)^{3 / 3} f_{1}^{\prime}(\omega) d \omega, \quad \omega \in(\pi / 2, \pi] \\
& F_{0}(\pi / 2)=-3 f_{1}^{\prime}(\pi / 2)
\end{align*}
$$

From (2.10), taking account of (2.7) and (2.8), we obtain the expansions

$$
\begin{align*}
& F_{1}(\omega)=3 b \omega^{-1 / 3}\left(1-\frac{2}{9} \omega^{2}-\frac{1}{135} \omega^{4}+\ldots\right) \\
& F_{1}(\pi-t)=\frac{2}{3} t^{1 / 3 / 3}\left(1-\frac{1}{3} t^{2}+\frac{2}{45} t^{4}+\ldots\right) \tag{2.11}
\end{align*}
$$

It can be shown that the function $F_{1}(\omega)$ satisfies the equation

$$
\begin{equation*}
F_{1}^{\prime}(\omega)+\frac{2}{3} \csc 2 \omega F_{1}(\omega)=-\operatorname{tg} \omega f_{1}^{\prime}(\omega) \tag{2.12}
\end{equation*}
$$

and is analytic in the interval $(0, \pi)$ and can be represented in the neighbourhood of the point $\omega=\pi / 2$ in the form

$$
F_{1}\left(\frac{\pi}{2}+t\right)=\sqrt{b}\left(\sqrt{2}-\frac{13}{6} t+\frac{49 \sqrt{2}}{144} t^{2}+\frac{59}{243} t^{3}+\frac{12829 \sqrt{2}}{124416} t^{4}+\ldots\right)
$$

The quantities $F_{1}(\omega), F_{1}^{\prime}(\omega)$ outside of the neighbourhood of the point $\omega=\pi / 2$ can be found using formulae (2.10) or by numerical integration of (2.12) using (2.11).

Let us put $\psi=\psi^{01}+\psi^{02}$ in (1.10) and change to the variables $\theta, \omega$. Equating terms of the order of $\theta^{-y / 3}$ in the expansions of the left-hand and right-hand sides of (1.1) in powers of $\theta$, we obtain

$$
\begin{align*}
& P f_{2}^{\prime \prime}+Q f_{2}^{\prime}+R f_{2}=S, \quad P=4 \sin ^{2} \omega\left(1-\frac{5}{9} \sin ^{2} \omega\right) f_{1}^{2}  \tag{2.13}\\
& Q=\frac{14}{3} \sin 2 \omega\left(1-\frac{10}{21} \sin ^{2} \omega\right) f_{1}^{2}-12 \sin ^{2} \omega\left(1-\frac{25}{27} \sin ^{2} \omega\right) f_{1} f_{1}^{\prime}+3 \sin ^{3} \omega \cos \omega f_{1}^{\prime 2} \\
& R=8 \sin ^{2} \omega\left(1-\frac{2}{9} \sin ^{2} \omega\right) f_{1} f_{1}^{\prime \prime}-\frac{14}{3} \sin 2 \omega\left(1+\frac{8}{21} \sin ^{2} \omega\right) f_{1} f_{1}^{\prime}+\frac{76}{9} f_{1}^{2}- \\
& -3 \sin ^{2} \omega\left(1-\frac{62}{27} \sin ^{2} \omega\right) f_{1}^{\prime 2} \\
& S=\alpha F_{1}\left[-\frac{200}{27} f_{1}^{2}+\frac{28}{9} \sin 2 \omega\left(1+\frac{6}{7} \sin ^{2} \omega\right) f_{1} f_{1}^{\prime}+\frac{10}{3} \sin ^{2} \omega \cos 2 \omega f_{1}^{\prime 2}-\right. \\
& \left.-8 \sin ^{2} \omega\left(1-\frac{1}{3} \sin ^{2} \omega\right) f_{1} f_{1}^{\prime \prime}\right]-\alpha f_{1}^{\prime} \sin 2 \omega\left[\frac{4}{9} f_{1}^{2}-\frac{2}{3} \sin ^{2} \omega f_{1} f_{1}^{\prime}+\sin ^{2} \omega f_{1}^{\prime 2}\right]+ \\
& +a_{1}\left[\sin ^{2} \omega \cos ^{3} \omega\left(6 f_{1} f_{1}^{\prime 2}-4 f_{1}^{2} f_{1}^{\prime \prime}\right)-\frac{64}{27} \operatorname{ctg}^{2} \omega f_{1}^{3}-\frac{4}{3} \cos ^{2} \omega\left(1-6 \sin ^{2} \omega\right) f_{1}^{2} f_{1}^{\prime \prime}-\right. \\
& \left.-\sin ^{2} \omega \cos ^{4} \omega f_{1}^{\prime 3}\right]+\left(c_{1}-b_{1}\right) \sin ^{4} \omega \cos ^{2} \omega f_{1}^{\prime 3}+\left(\frac{16}{9} c_{1}-\frac{32}{9} b_{1} \cos ^{2} \omega\right) \sin ^{2} \omega f_{1}^{2} f_{1}^{\prime}+ \\
& +\left(\frac{8}{3} c_{1}-\frac{8}{9} b_{1}\right) \sin ^{3} \omega \cos ^{\prime} \omega f_{1} f_{1}^{\prime 2}-\frac{16}{9} b_{1} \sin ^{3} \omega{\cos \omega f_{1}^{2} f_{1}^{\prime \prime}}^{a_{1}=\left.\frac{\lambda_{a}}{\left(1-M_{a}^{2}\right)^{3 / 2}} \frac{d}{d \lambda}\left(1-M^{2}\right)\right|_{\lambda=\lambda_{a}}} \\
& b_{1}=2\left(1-M_{a}^{2}\right)^{-1 / 2}, c_{1}=\left(1+M_{a}^{2}\right)\left(1-M_{a}^{2}\right)^{-1 / 2}
\end{align*}
$$

Using (2.7), (2.8) and (2.11), it can be shown that, when $\omega \rightarrow 0$ and $\omega=\pi-t, t \rightarrow 0$ the expansions

$$
\begin{align*}
& P(\omega)=b^{2} \omega^{10 / 3}\left(4-\frac{40}{9} \omega^{2}+\ldots\right), \quad P(\pi-t)=t^{25 / 3}\left(4-\frac{64}{9} t^{2}+\ldots\right) \\
& Q(\omega)=b^{2} \omega^{7 / 3}\left(\frac{8}{3}-\frac{20}{27} \omega^{2}+\ldots\right), \quad Q(\pi-t)=t^{19 / 3}\left(\frac{4}{3}-\frac{160}{27} t^{2}+\ldots\right) \\
& R(\omega)=b^{2} \omega^{4 / 3}\left(-\frac{8}{9}+\frac{428}{81} \omega^{2}+\ldots\right), \quad R(\pi-t)=t^{16 / 3}\left(-\frac{20}{9}+\frac{1856}{81} t^{2}+\ldots\right)  \tag{2.14}\\
& S(\omega)=b^{3} \omega^{3} \sum_{n=1}^{\infty} \sigma_{n} \omega^{2 n-2}, \quad S(\pi-t)=t^{9} \sum_{n=1}^{\infty} v_{n} n^{2 n-2} \\
& \sigma_{1}=\frac{8}{3}\left(a_{1}+c_{1}-b_{1}-2 \alpha\right), \quad v_{1}=\frac{128}{3}\left(b_{1}-c_{1}-a_{1}-\frac{1}{2} \alpha\right)
\end{align*}
$$

hold.
It follows from (2.9) and (2.13) that the following boundary-value problem holds in the case of the function $\varphi_{2}(\omega)=\sin ^{1 / 3} \omega f_{2}(\omega)$

$$
\begin{gather*}
P_{1} \varphi_{2}^{\prime \prime}+Q_{1} \varphi_{2}^{\prime}+R_{1} \varphi_{2}=S_{1}, \quad P_{1}=P, \quad Q_{1}=-\frac{2}{3} \operatorname{ctg} \omega P+Q  \tag{2.15}\\
R_{1}=\left(\frac{4}{9} \operatorname{ctg}^{2} \omega+\frac{1}{3}\right) P-\frac{1}{3} \operatorname{ctg} \omega Q+R, \quad S_{1}=\sin ^{1 / 3} \omega S \\
\varphi_{2}^{\prime}(0)=0, \quad \varphi_{2}(\pi)=0 \tag{2.16}
\end{gather*}
$$

By substituting (2.14) into (2.15), it can be shown that $\varphi_{2}(\omega)$ can be expanded in the form

$$
\begin{equation*}
\varphi_{2}(\omega)=\sum_{n=1}^{\infty} p_{n} \omega^{n-1}, \quad \varphi_{2}(\pi-t)=\sum_{n=1}^{\infty} q_{n} t^{2 n} \tag{2.17}
\end{equation*}
$$

and, moreover, the relationships

$$
p_{2 j}=\alpha_{j} p_{2}, \quad p_{2 j+1}=\beta_{j}+\gamma_{j} p_{1}, \quad q_{j}=\mu_{j}+\kappa_{j} q_{1}, \quad j=1,2, \ldots
$$

hold in which the coefficients $\alpha_{j}, \beta_{j}, \gamma_{j}, \mu_{j}, \kappa_{j}$ are expressed in terms of the coefficients of the expansions (2.14). In particular

$$
\begin{equation*}
p_{3}=\frac{1}{8} b \sigma_{1}-\frac{1}{2} p_{1}, \quad q_{2}=\frac{1}{32} v_{1}-\frac{5}{6} q_{1} \tag{2.18}
\end{equation*}
$$

The second of the conditions (2.16) is satisfied in the case of the expansions (2.17) and the first is equivalent to the condition $p_{2}=0$. The problem therefore reduces to searching for a $q_{1}$ for which, on integrating (2.15) numerically from the point $\omega=\pi-\varepsilon \quad(0<\varepsilon \ll 1)$ using (2.17) and (2.18) to determine the values of $\varphi_{2}(\pi-\varepsilon), \varphi_{2}^{\prime}(\pi-\varepsilon)$, a function $\varphi_{2}(\omega)$ is obtained which satisfies the condition $p_{2}=\varphi_{2}^{\prime}(0)=0$.

The right-hand side of Eq. (2.15) can be represented in the form

$$
\begin{equation*}
S_{1}=a_{1} S_{1 a}+k_{1} S_{1 k}+m_{1} S_{1 m}+n_{1} S_{1 n} \tag{2.19}
\end{equation*}
$$

where $k_{1}=\left(1-M_{a}^{2}\right)^{1 / 2}, m_{1}=k_{1} M_{a}^{2}, n_{1}=k_{1} M_{a}^{4}, S_{1 a}, S_{1 k}, S_{1 m}, S_{1 n}$ are unknown functions of $\omega$ which are independent of $a_{1}$ and $M_{a}$. It is therefore convenient to use the representation

$$
\begin{equation*}
\varphi_{2}=a_{1} \varphi_{2 a}+k_{1} \varphi_{2 k}+m_{1} \varphi_{2 m}+n_{1} \varphi_{2 n} \tag{2.20}
\end{equation*}
$$

and to determine each of the functions $\varphi_{2 a}, \varphi_{2 k}, \varphi_{2 m}, \varphi_{2 n}$ which depend solely on $\omega$ from the solution of the corresponding boundary-value problem which is obtained when (2.19) and (2.20) are substituted into (2.15) and (2.16).

Analysis shows that the expansions

$$
\begin{array}{ll}
\varphi_{2 a}(\omega)=b\left(-1+\frac{5}{6} \omega^{2}+\ldots\right), & \varphi_{2 a}(\pi-t)=2 t^{2}-3 t^{4}+\ldots \\
\varphi_{2 k}(\omega)=b\left(-2+O\left(\omega^{3}\right) \ldots\right), & \varphi_{2 k}(\pi-t)=-3 t^{2}+\frac{19}{6} t^{4}+\ldots \\
\varphi_{2 m}(\omega)=b\left(\frac{8}{3}+\frac{2}{3} \omega^{2}+\ldots\right), & \varphi_{2 m}(\pi-t)=\frac{22}{3} t^{2}-\frac{67}{9} t^{4}+\ldots \\
\varphi_{2 n}(\omega)=b\left(-\frac{2}{3}-\frac{2}{3} \omega^{2}+\ldots\right), & \varphi_{2 n}(\pi-t)=-\frac{13}{3} t^{2}+\frac{77}{18} t^{4}+\ldots
\end{array}
$$

hold when $\omega \rightarrow 0$ and $\omega=\pi-t, t \rightarrow 0$.
The dependences of $\varphi_{2 a}, \varphi_{2 k}, \varphi_{2 m}, \varphi_{2 n}$ on $\omega$ are shown in Fig. 2 by curves 2-5.
Let $\varphi_{2}(\omega)$ be the solution of (2.15), (2.16). Then $\psi^{\infty 2}=\theta^{1 / 3} \sin ^{-j / 3} \omega \varphi_{2}(\omega)=\mu^{1 / 3} \varphi_{2}(\omega)$. Hence, the families $\psi^{\infty 2}=c>0$ and $\psi^{02}=c<0(c=$ const $)$ in the $(\sigma, \theta)$-plane consist of similar curves and they tend to zero as $\mu^{1 / 3}$ on approaching the singular point from any direction $\omega=$ const $\psi^{02}$.
3. Let us assume the function $\Psi^{0}$ has been found with sufficiently high accuracy.

The function $\chi=\psi-\psi^{0}$ must serve as a solution of the boundary-value problem

$$
\begin{align*}
& L(\chi)=N\left(\psi^{0}+\chi, Y\left(\psi^{0}+\chi\right)\right)-\dot{L}\left(\psi^{0}\right), \quad(\tau, \theta) \in \Sigma_{0}  \tag{3.1}\\
& \chi=-\psi^{0} \quad \text { in } A B B_{1} C D, \quad \chi_{\theta}=0 \text { in } A D \tag{3.2}
\end{align*}
$$

There is practical interest in the cases when the magnitude of $\lambda_{c}$ is close to $\lambda_{a}$ (the magnitude of $\tau_{0}$ is close to unity) and the gradients of the quantities which are determined in the interval $A D$ and the part of the domain $\Sigma_{o}$ adjoining it are large. When the problem is solved numerically, this leads to the need for a transformation of the independent variables.

We shall use the following transformations which convert $\Sigma_{0}$ into $\Sigma_{1}=\{(\xi, \eta) \mid 0<\xi<1$, $0<\eta<1\}$. When

$$
\begin{equation*}
\tau_{0}<2, \quad \frac{1}{2} \theta_{0}\left(\alpha \tau_{0}\left(\tau_{0}-1\right)\left[\ln 2-\ln \left(\tau_{0}-1\right)\right]\right\}^{-1} \geqslant 1 \tag{3.3}
\end{equation*}
$$

we put [13, Section 5.6]

$$
\begin{aligned}
& \xi=f(\tau)=F\left(\beta_{1}, \tau / \tau_{0}\right), \quad \eta=g(\theta)=1-F\left(\beta_{2}, 1-\theta / \theta_{0}\right) \\
& F(x, y)=\ln [(x+y) /(x-y)][\ln [(x+1) /(x-1)]\}^{-1}
\end{aligned}
$$

and determine the parameters $\beta_{1}, \beta_{2}\left(1<\beta_{1}, \beta_{2}<\infty\right)$ from the conditions

$$
\begin{equation*}
f(1)=0,5, \quad f^{\prime}(1)=\alpha g^{\prime}(0) \tag{3.4}
\end{equation*}
$$

(conditions (3.3) guarantee the unique solvability of Eqs (3.4) with respect to $\beta_{1}$ and $\beta_{2}$ ). When only the first of the inequalities (3.3) is satisfied, we put $\xi=f(\tau), f(1)=0.5, \quad \eta=\theta / \theta_{0}$. When $\tau_{0} \geqslant 2$ let $\xi=\tau / \tau_{0}, \eta=\theta / \theta_{0}$.

Equation (3.1) is written in the form

$$
\begin{align*}
& \Gamma(\chi)=N\left(\psi^{0}+\chi, \quad Y\left(\psi^{0}+\chi\right)\right)-L\left(\psi^{0}\right)  \tag{3.5}\\
& \Gamma(\chi)=A \chi_{\eta \eta}+B \chi_{\xi \xi}+C \chi_{\xi}+D \chi_{\eta} \\
& A=\left(1-M^{2}\right) \eta_{\theta}^{2}, \quad B=\tau^{2} \xi_{\tau}^{2}, \quad D=\left(1-M^{2}\right) \eta_{\theta \theta}, \quad C=\tau^{2} \xi_{\pi}+\left(1+M^{2}\right) \tau \xi_{\tau}
\end{align*}
$$

We introduce a uniform rectangular grid in the $(\xi, \eta)$-plane with step sizes $\Delta \xi$ with respect to $\xi$ and $\Delta \eta$ with respect to $\eta$ and with grid points at the points ( $\xi_{i}, \eta_{j}$ ), where $\xi_{1}=i \Delta \xi$, $\eta_{j}=i \Delta \eta, i=0,1, \ldots, I, j=0,1, \ldots, J, \Delta \xi I=\Delta \eta J=1$. Let $\xi_{s}$ be the value of $\xi$ corresponding to $\tau=1$ and let $m$ be an index for which $\xi_{m-1} \leqslant \xi_{a}, \xi_{m}>\xi_{a}$. We shall denote quantities calculated at a point ( $\xi_{i}, \eta_{j}$ ) with the subscripts $i, j$ and those calculated on the line $\xi=\xi_{i}$ by the subscript $i$.

The determination of $\chi$ reduces to solving an iterative sequence of linear boundary-value difference problems: $\chi^{(n+1)}(n+1)$ (the approximation of the required function) is found using the scheme

$$
\chi^{(n+1)}=(1-w) \chi^{(n)}+w \chi^{(n+1 / 2)}, \quad 0<w \leqslant 1, \quad n=0,1, \ldots
$$

and the solution of the difference problem

$$
\begin{align*}
& \Lambda(\chi)_{i, j}=T_{i, j}^{(n)}, \quad i=1,2, \ldots, I-1, \quad j=1,2, \ldots, J-1 \\
& \Lambda(\chi)_{i, j}=A_{i, j}\left(\chi_{i, j+1}-2 \chi_{i, j}+\chi_{i, j-1}\right) / \Delta \eta^{2}+D_{i, j}\left(\chi_{i, j+1}-\chi_{i, j-1}\right) / 2 \Delta \eta+ \\
& +B_{i}\left(\chi_{i+1, j}-2 \chi_{i, j}+\chi_{i-1, j}\right) / \Delta \xi^{2}+C_{i}\left(\chi_{i+1, j}-\chi_{i-1, j}\right) / 2 \Delta \xi \\
& T^{(n)}=N\left(\psi^{0}+\chi^{(n)}, \quad Y^{(n)}\right)-L\left(\Psi^{0}\right) \\
& \Lambda(\chi)_{i, 0}=U_{i, 0}^{(n)}, \quad \chi_{i,-1}=\chi_{i, 1}, \quad i=m, m+1, \ldots, I-1  \tag{3.6}\\
& U^{(n)}=\tau^{2}\left(\psi_{\tau}^{0}+\chi_{\tau}^{(n)}\right)^{2} / Y^{(n)}-L\left(\Psi^{0}\right) \\
& \chi_{0, j}=-\psi_{0, j}^{0}, \quad \chi_{I, j}=-\psi_{I, j}^{0}, \quad j=0,1, \ldots, J \\
& \chi_{i, J}=-\Psi_{i, J}^{0}, \quad i=0,1, \ldots, I ; \quad \chi_{i, 0}=0, \quad i=0,1, \ldots, m-1
\end{align*}
$$

is accepted for $\chi^{(n+/ 2)}$.
The method of successive upper relaxation is used in the implementation of the difference scheme (3.6). The partial derivatives of $\chi^{(n)}$, which occur in the expressions $T^{(n)}, U^{(n)}$ are calculated on the basis of a spline approximation of the grid values of $\chi^{(n)}$.

As a rule, domains of negative values of the quantities $\psi^{(n)}=\psi^{0}+\chi^{(n)}, Y\left(\psi^{(n)}\right)+\psi_{\theta}^{(n)} \sin \theta$, arise outside of the neighbourhood of the singular point during the iterative process which subsequently become smaller and disappear. The following technique is used in order that the expression $2 Y\left(\psi^{(n)}+\psi_{\theta}^{(n)}\right) \sin \theta$ should not vanish (and $T^{(n)}, U^{(n)}$ become infinite) and that the iterative process should not diverge. If in $\Sigma_{1}^{\prime}=\left\{\left(\xi_{i}, \quad \eta_{j}\right) \in \Sigma_{1}\right\} \min \left[Y\left(\psi^{(n)}\right)+0.5 \psi_{\theta}^{(n)} \sin \theta\right]=$ $-m^{(n)}<0$, then we put $Y^{(n)}=Y\left(\psi^{(n)}\right)+3 m^{(n)}\left\{1-\exp \left[\delta_{1}\left(\xi-\xi_{a}\right)^{2}+\delta_{2} \eta^{2}\right]\right\}$, and, otherwise we put $Y^{(n)}=Y\left(\psi^{(n)}\right)$.
The function $\psi^{01}+\psi^{02}$ generates a broad range of negative values of $Y\left(\psi^{01}+\psi^{02}\right)$. Allowing for this, it is convenient to put $\psi^{n}=\psi^{n 1}+\psi^{n 2} \exp \left[\delta_{3}(\tau-1)^{2}+\delta_{4} \theta^{2}\right]$, where $\delta_{3}, \delta_{4} \in[-20,-10]$. A function $\psi^{0}$ constructed using the technique described above retains all the required properties, which are inherent in the sum $\psi^{01}+\psi^{02}$, in the neighbourhood of the singular point and, at the same time, it is such that $Y\left(\psi^{0}\right)>0$ in $\Sigma_{0}$.

The use of formula (1.12) is not the only possible method for determining $Y\left(\psi^{(n)}\right)$. Moreover, this method does suffer from the drawback that the maximum errors which arise in determining $\chi^{(n)}$ in the neighbourhood of a singular point, as a result of integration, extend upwards from and to the right of this neighbourhood. Formula (1.2) is therefore used to determine $Y\left(\psi^{(n)}\right)$ only at the beginning of the iterative process. Later, $Y\left(\psi^{(n)}\right)$ is determined using alternate integration of relationships (1.8) along those trajectories which pass around the neighbourhood of the singular point or just terminate at it. here, a spline approximation of the partial derivatives of $\chi^{(n)}$ occurring in expressions (1.8) is used.

It can be shown that the condition $G_{\theta}=H_{t}$, which follows from (1.8), is equivalent to Eq. (1.10). When this condition is satisfied, the value of $y$, found at an arbitrary point of the domain $\Sigma_{0}$ by integration of the expression $d y=G d \tau+H d \theta$, is independent of the integration path. This consideration can be made use of in controlling the accuracy of the solution obtained.

The proposed method of calculation can be used to investigate compressible liquid and gas flows with different dependences $M(\lambda), v(\lambda)$. An experiment we carried out suggests that, in the case of the relations $M(\lambda), v(\lambda)$, which hold in the case of an ideal gas, there is a fairly wide range of governing parameters for which the process of successive approximations, which has been described above, converges in a stable manner.

Having determined $\psi(\tau, \theta), r(\tau, \theta)$ simultaneously using the method described, there is no difficulty in finding all the required characteristics of the flow using (1.7)
4. We know [14] that, for many liquids, the relation between the pressure $p$ and the density $\rho$ in an isentropic process is given by the formula

$$
\begin{equation*}
\frac{p+B}{p_{s}+B}=\left(\frac{\rho}{\rho_{s}}\right)^{k} \tag{4.1}
\end{equation*}
$$

where $p_{s}, \rho_{s} B, k$ are certain constants. For water $k=7.15$ [15]. The relationships

$$
\begin{align*}
& M^{2}=\frac{2}{k+1} \lambda^{2}\left(1-m \lambda^{2}\right)^{-1}, \quad \rho=\rho_{0}\left(1-m \lambda^{2}\right)^{1 /(k-1)}  \tag{4.2}\\
& p=p_{0}+\frac{k+1}{2 k} \rho_{0} a_{*}^{2}\left[\left(1-m \lambda^{2}\right)^{k /(k-1)}-1\right], \quad m=\frac{k-1}{k+1} \tag{4.3}
\end{align*}
$$

which are used below ( $a_{0}$ is the critical velocity and $p_{0}$ is the value of $p$ at the stagnation point) are obtained from Bernoulli's equation and (4.1) subject to the assumptions which have been made.

Let $p_{a}, \rho_{a}, V_{a}$ be the pressure, density and velocity of the free flow, $p_{c}$ the pressure in the cavern, $X$ the cavitator resistance and $R_{0}$ the radius of the cavitator (the value of $r$ at the point $C$ ). Moreover, $R_{0}=1$. Using (4.2) and (4.3), we obtain the expressions

$$
\begin{gather*}
Q=\frac{k+1}{k \lambda_{a}^{2}\left(1-m \lambda_{a}^{2}\right)^{1 /(1-k)}\left[\left(1-m \lambda_{a}^{2}\right)^{k /(k-1)}-\left(1-m \lambda_{c}^{2}\right)^{k /(k-1)}\right]}  \tag{4.4}\\
C_{x}=\frac{2\left(1-m \lambda_{a}^{2}\right)^{1 /(1-k)}}{r^{2}\left(\tau_{0}, \theta_{0}\right)} \int_{0}^{\tau} r^{2}\left(\tau, \theta_{0}\right)\left(1-m \lambda_{a}^{2} \tau^{2}\right)^{1 /(k-1)} \tau d \tau \tag{4.5}
\end{gather*}
$$

for the cavitation number $Q=2\left(p_{a}-p_{c}\right) /\left(\rho_{a} V_{a}^{2}\right)$ and the drag coefficient $C_{x}=2 X /\left(\pi \rho_{a} V_{a}^{2} R_{0}^{2}\right)$. The equality $Q=\tau_{0}^{2}-1$. is obtained from (4.4) in the limit when $\lambda_{a}, \lambda_{c} \rightarrow 0$. When $\theta_{0}=\pi$, we have $r\left(\tau, \theta_{0}\right)=r\left(\tau_{0}, \theta_{0}\right)$ and, in this case, it therefore follows from (4.5) that

$$
\begin{equation*}
C_{x}=\frac{k+1}{k \lambda_{a}^{2}}\left(1-m \lambda_{a}^{2}\right)^{1 /(1-k)}\left[1-\left(1-m \lambda_{c}^{2}\right)^{k /(k-1)}\right] \quad\left(\theta_{0}=\pi\right) \tag{4.6}
\end{equation*}
$$

$C_{x}=\tau_{2}^{0}=1+Q$ is oblained from (4.6) in the limit subject to the additional condition $\lambda_{a}, \lambda_{c} \rightarrow 0$.
Let us consider a cavitator where the part around which the flow occurs is in the form of a cone with an aperture angle $\theta_{0}$ in the range [ $\pi / 2, \pi$ ] (a disc or cavitator with a conical channel). Let $E$ and $F$ be points on the arc $C D G$ of the free surface at which $\theta=\pi / 2$ and $\theta=-\pi / 2$ respectively. Let $R_{1}$ and $R_{2}$ be the values of $r$ at points $E$ and $D$ ( $R_{2}$ is the radius of the cavern in the plane of symmetry), let $L_{0}, L_{1}$ and $L_{2}$ be the projections of the vectors $B H, C G$ and $E F$ on to the $x$-axis ( $L_{2}$ is the length of the cavern, $L_{1}=L_{0}-2 R_{0} \operatorname{ctg} \theta_{0}$ ), and let $K_{1}$ be the curvature of the arc $C D G$ at point $D$.

One version of the calculation using the proposed model assumes that the values of $k, \theta_{0}, Q, \lambda_{c}$ are specified. However, for the case when $\lambda_{c}=0$ (an incompressible fluid), the solution is independent of $k$. Furthermore, when $\lambda_{c}=0$, the solution is general for all fluid models.

In Table 1, we present the values of $C_{x}, L_{2}$ and $R_{2}$, obtained for a series of values of $Q$ in the calculation of the cavitational flow around a disc ( $\theta_{0}=\pi / 2$ ) by an incompressible fluid using the method which has been described on an $I \times J=50 \times 50$ grid and also the corresponding values from [4]. A comparison shows that the differences are less than one percent. A similar estimate may be obtained by comparing the data presented below with the values of $C_{x}, L_{2} R_{2}$ found using Guzevskii's approximation formulae [3].
5. Calculations were carried out on an $I \times J=50 \times 100$ grid for flows of an incompressible fluid around cavitators with aperture angles of the cones $\theta_{0}=\pi(6+n) / 12(n=0,1, \ldots, 6)$ for $Q=0.15 ; 0.2 ; 0.3 ; 0.4 ; 0.5$. Approximation formulae for the parameter $C_{x}, K_{1}, R_{1}, R_{2}, L_{1}, L_{2}$ of the following form were constructed on the basis of the results obtained

Table 1

| $Q$ | $R_{2}$ | $R_{2}[4]$ | $L_{2}$ | $L_{2}[4]$ | $C_{x}$ | $C_{x}[4]$ |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| 0.2636 | 2.1184 | 2.115 | 10.043 | 10 | 1.0539 | 1.0513 |
| 0.1477 | 2.6773 | 2.678 | 20.121 | 20 | 0.9559 | 0.9516 |
| 0.1048 | 3.1045 | 3.109 | 30.105 | 30 | 0.9198 | 0.9150 |
| 0.0819 | 3.4607 | 3.471 | 40.176 | 40 | 0.9021 | 0.8955 |
| 0.0676 | 3.7693 | 3.788 | 50.257 | 50 | 0.8917 | 0.8833 |

$$
\begin{array}{ll}
C_{x}^{0}=a+b(1+Q)^{-1}+c Q, & d=d_{1}+d_{2} \ln \omega_{1}+d_{3} \ln ^{2} \omega_{1} \\
K_{1}^{0}=a Q+b Q^{2}+c Q^{3}, & d=d_{1}+d_{2} \ln \omega_{2}+d_{3} \omega_{2}^{2} \\
R_{1}^{0}=1+a+b Q^{-1} \ln Q+c Q^{-1}, & d=d_{1} \omega_{3}+d_{2} \omega_{3}^{2}+d_{3} \omega_{3}^{3}  \tag{5.1}\\
P^{0}=a+b Q^{-1} \ln Q+c Q^{-1}, \quad d=d_{1}+d_{2} \ln \omega_{2}+d_{3} \omega_{2}^{2}, \quad P^{0}=R_{2}^{0}, L_{1}^{0}, L_{2}^{0} \\
\omega_{1}=\theta_{0}+\frac{\pi}{12}, \quad \omega_{2}=\theta_{0}+\frac{\pi}{2}, \quad \omega_{3}=\theta_{0}-\frac{\pi}{2} ; \quad d=a, b, c
\end{array}
$$

(values of the parameters in the case when $\lambda_{c}=0$ are given the superscript 0 ).
The values of the coefficients $a_{j}, b_{j}$ and $c_{j}$ for the approximation formulae and the values $\varepsilon$ of the maximum relative errors of the approximation are shown in Table 2. The differential characteristic $K_{1}$ is calculated with a lower accuracy than the remaining integral and local characteristics, and the value of $\varepsilon$ for $K_{1}$ is therefore substantially greater than for the other parameters.

Table 2

|  | $d_{j}$ | $j=1$ | 2 | 3 | $10^{4} \times \varepsilon$ |
| :---: | :---: | :---: | :---: | :---: | :---: |
| $C_{x}^{0}$ | $a_{j}$ | 0.08016 | 1.35824 | -0.49618 | 5 |
|  | $b_{j}$ | 0.34607 | -0.48921 | 0.16908 |  |
|  | $c_{j}$ | 0.80092 | 0.26089 | -0.07998 |  |
| $\kappa_{1}^{0}$ | $a_{j}$ | 0.04769 | -0.01338 | 0.00018 | 137 |
|  | $b_{j}$ | 1.08518 | -0.48366 | 0.01198 |  |
|  | $c_{j}$ | -0.38103 | 0.18322 | -0.00483 |  |
| $R_{1}^{0}$ | $a_{j}$ | 0.01638 | 0.01924 | -0.01035 | 13 |
|  | $b_{j}$ | 0.00356 | 0.00025 | -0.00058 |  |
|  | $c_{j}$ | 0.00818 | 0.00063 | -0.00142 |  |
| $R_{2}^{0}$ | $a_{j}$ | 0.61572 | 0.37494 | -0.00857 | 16 |
|  | $b_{j}$ | $-0.05025$ | 0.14946 | -0.00319 |  |
|  | $c_{j}$ | $-0.05503$ | 0.51617 | $-0.01131$ |  |
| $L_{1}^{0}$ | $a_{j}$ | 0.53405 | -0.32871 | 0.00528 | 22 |
|  | ${ }^{b_{j}}$ | $-0.57861$ | -0.00703 | -0,00194 |  |
|  | $c_{j}$ | $-0.19199$ | 2.18048 | -0.05274 |  |
| $L_{2}^{0}$ | $a_{j}$ | 0.61528 | -0.46052 | 0.01232 | 20 |
|  | $b_{j}$ | -0.57545 | -0,01431 | -0.00142 |  |
|  | $c_{j}$ | -0.18529 | 2,16486 | -0.05160 |  |

The following expression is obtained from (5.1) for the drag coefficient of the disc $(\theta=\pi / 2)$ in an incompressible fluid

$$
\begin{equation*}
C_{x}^{0}=0.7208+0.1118(1+Q)^{-1}+0.9296 Q \quad(0.15 \leqslant Q \leqslant 1) \tag{5.2}
\end{equation*}
$$

It is interesting to compare (5.2) with the approximation formulae

$$
\begin{gather*}
C_{x}^{0}=(0.827+0.026 Q)(1+Q) \quad(0.1 \leqslant Q \leqslant 0.6)  \tag{5.3}\\
C_{x}^{0}=0.82825+0.86 Q \quad(0 \leqslant Q \leqslant 0.25) \tag{5.4}
\end{gather*}
$$

of which the first, which is given in [16, p. 458] was constructed on the basis of a graph from [17] and the second is obtained, when $\theta_{0}=\pi / 2$ from Guzevskii's formula for a cone [3]. The differences in the values of $C_{x}^{0}$, calculated using formulae (5.2) and (5.3) in the interval $0.1 \leqslant Q \leqslant 1$ do not exceed $0.3 \%$ and $0.075 \%$ in the interval $0.25 \leqslant Q \leqslant 1$. The difference in the values of $C_{x}^{0}$, calculated using formulac (5.2) and (5.4) do not exceed $0.15 \%$ in the range $0.1 \leqslant Q \leqslant 0.5$ and $0.06 \%$ in the range $0.15 \leqslant Q \leqslant 0.4$.
The nature of the approximation relations (5.1) can be described by the inequalities

$$
\begin{gather*}
\frac{\partial L_{1}^{0}}{\partial Q}<0, \frac{\partial L_{2}^{0}}{\partial Q}<0, \quad \frac{\partial R_{2}^{0}}{\partial Q}<0, \frac{\partial K_{1}^{0}}{\partial Q}>0, \frac{\partial C_{x}^{0}}{\partial Q}>0, \frac{\partial C_{x}^{0}}{\partial \theta_{0}}>0  \tag{5.5}\\
\frac{\partial S^{0}}{\partial \theta_{0}} \geqslant 0, \quad S^{0}=-K_{1}^{0}, R_{1}^{0}, R_{2}^{0}, L_{1}^{0}, L_{2}^{0} \tag{5.6}
\end{gather*}
$$

where the inequalities (5.5) hold over the whole computational domain $0.15 \leqslant Q \leqslant 1, \pi / 2 \leqslant \theta_{0} \leqslant \pi$ while (5.6) are satisfied outside a certain neighbourhood of the range $0.15 \leqslant Q \leqslant 1, \theta_{0}=\pi$, where the values of $\left|\partial S^{0} / \partial \theta_{0}\right|$ are small compared with the corresponding values when $\theta_{0}=\pi / 2$.

The inequalities

$$
\frac{\partial\left(L_{2}^{0} / L_{1}^{0}\right)}{\partial \theta_{0}}>0, \quad \frac{\partial\left(L_{2}^{0} / L_{1}^{0}\right)}{\partial Q}>0, \quad \frac{\partial\left(R_{2}^{0} / L_{2}^{0}\right)}{\partial Q}>0
$$

also hold for the whole of the computational domain.
The quantities $R_{2}^{0} / L_{2}^{0}$ and $C_{x 1}^{0}=C_{x}^{0} /\left(R_{2}^{0}\right)^{2}\left(C_{x 1}\right.$ is the drag coefficient determined over the midsectional area of the cavern) depend weakly on $\theta_{0}$ and the quantity $R_{2}^{0} / L_{2}^{0}$ attains its maximum values when $\theta_{0}=\pi / 2$. One unexpected fact is that the quantity $R_{0}$, which characterizes the position of the points for which $\theta= \pm \pi / 2$, does not take its maximum values on the boundary of the computational domain (when $Q=0.15$ ) but when $Q=0.3$ for all values of $\theta_{0}$ in the range $(\pi / 2, \pi)$.

The dependence of some of the parameters on $\theta_{0}$ when $\lambda_{c}=0$ and $Q=0.15$ is shown in Fig. 3. Curves $1-4$ correspond to the quantities $0.1 \times L_{2}^{0}, C_{x}^{0}+1,100 \times K_{1}^{0}, R_{2}^{0}-1$. Curve 5 shows how $C_{x}^{0}+1$ depends on $\theta_{0}$; it was obtained on the assumption that the pressure distribution along the generatrix of the cone can be found from the solution of the corresponding planar problem, as was done in [18, 19].

In Fig. 4, curves 1-3 depict the dependence $L_{0}^{0}\left(\theta_{0}\right)$ for $Q=0.15,0.3$ and 1 , respectively. For each $Q$, a $\omega_{0}=\omega_{0}(Q)$ exists such that $L_{0}^{0}=0$ when $\theta_{0}=\omega_{0}\left(d \omega_{0} / d Q<0\right), L_{0}^{0}<0$ when $\omega_{0}<\theta_{0} \leqslant \pi, L_{0}^{0} \rightarrow-\infty$ when $\theta_{0} \rightarrow \pi$. The domain occupied by the flow in the $(x, r)$-plane is therefore two-sheeted when $\omega_{0}<\theta_{0} \leqslant \pi$. A diagram of the flow when $\omega_{0}<\theta_{0} \leqslant \pi$ and $\theta_{0}=\pi$ is shown in Figs $5(a)$ and (b).
6. Calculations were carried out on the cavitational flow around a disc $\left(\theta_{0}=\pi / 2\right)$ by a stream of water $(k=7.15)$ for $Q=0.15 ; 0.2 ; 0.3 ; 0.4 ; 0.5 ; M_{c}^{2}=0.2 ; 0.4 ; 0.6 ; 0.8 ; 1\left(M_{c}\right.$ is the value of the Mach number when $\lambda=\lambda_{c}$ ) on an $I \times J=50 \times 50$ grid. Approximation formulae were constructed for the parameters $C_{x}, K_{1}$, $L_{2}, R_{2}\left(L_{0}=L_{1}=L_{2}, R_{1}=1\right.$ when $\left.\theta_{2}=\pi / 2\right)$ on the basis of the results obtained. These have the following form


Fig. 3.


Fig. 4.


Fig. 5.


Fig. 6.

$$
\begin{align*}
& C_{x}=\alpha C_{x}^{0}, \quad L_{2}=\beta L_{2}^{0}, \quad K_{1}=\gamma K_{1}^{0}, \quad R_{2}=\delta R_{2}^{0}  \tag{6.1}\\
& \mu=1+f M_{c}^{2}+g M_{c}^{3}+h M_{c}^{4}, \quad \mu=\alpha, \beta, \gamma, \delta, \quad d=d_{1}+d_{2} Q^{-1} \ln Q+d_{3} Q^{-1}, \quad d=f, g, h
\end{align*}
$$

Here, $C_{x}^{0}, L_{2}^{0}, K_{1}^{0}, R_{2}^{0}$ are functions of $Q$ obtained in accordance with formulae (5.1) and Table 2 when $\theta_{0}=\pi / 2$. The values of the coefficients $f_{i}, g_{i}, h_{i}$ for the approximation formulae (6.1) and of $\varepsilon$, the maximum relative errors in the approximation are presented in Table 3.

Table 3

|  | $d_{j}$ | $j=1$ | 2 | 3 | $10^{4} \times \varepsilon$ |
| :---: | :---: | :---: | :---: | :---: | :---: |
| $\alpha$ | $f_{j}$ | -0.00599 | 0.03688 | 0.10945 | 9 |
|  | $g_{j}$ | -0.01706 | -0.02887 | -0.08055 |  |
|  | $h_{j}$ | 0.01808 | 0.00201 | 0.00992 |  |
| $\beta$ | $f_{j}$ | 0.29589 | -0.01529 | -0.02098 | 23 |
|  | $g_{j}$ | -0.57432 | 0.13310 | 0.30976 |  |
|  | $h_{j}$ | 0.28978 | -0.09167 | $-0.20660$ |  |
| $\gamma$ | $f_{j}$ | -0.50861 | 0.05969 | 0.10518 | 127 |
|  | $\mathrm{g}_{j}$ | 0,89609 | -0.23137 | $-0.51375$ |  |
|  | $h_{j}$ | -0.42967 | 0.14014 | 0.30676 |  |
| $\delta$ | $f_{j}$ | -0.00028 | 0.01514 | 0.04757 | 11 |
|  | $8{ }^{\prime}$ | -0.02871 | -0.01376 | -0.03329 |  |
|  | $h_{j}$ | 0.01245 | 0.00858 | 0.00988 |  |

The nature of the dependence of the quantities $\alpha, \beta$ and $\gamma$ on $Q$ and $M_{c}$ in the domain $Q \in[0.15,1]$, $M_{c} \in[0,1]$ can be described by the inequalities

$$
\frac{\partial \alpha}{\partial M_{c}}>0, \quad \frac{\partial \alpha}{\partial Q}<0, \quad \frac{\partial \beta}{\partial M_{c}}>0, \quad \frac{\partial \beta}{\partial Q}<0, \quad \frac{\partial \gamma}{\partial M_{c}}<0, \quad \frac{\partial \gamma}{\partial Q}>0
$$

Hence, as $M_{c}$ increases for a fixed value of $Q \in[0.15,1], C_{x}$ and $L_{2}$ become larger while $K_{1}$ decreases and, moreover, the change in the parameters is greater, the smaller the value of $Q$.
The parameters $\alpha, \beta, \gamma$ and $\delta$ as functions of $M_{c}^{2}$ when $Q=0.15,0.35$ and 1 are shown in Fig. 6 (curves 1-3 respectively). The relation $\delta\left(M_{c}, Q\right)$ is quite complex. As $Q$ decreases, the value of $M_{c}$ at which $\delta\left(M_{c}, Q\right)$ attains its maximum value $\delta_{m}$ decreases, but $\delta_{m}$ itself increases. When $Q$ is reduced, the magnitude of $\delta(1, Q)$ increases when $Q \in[1,1]$, where $q=0.235$ and falls off when $Q \in[0.15, q]$.
The greatest change in the parameters $\alpha, \beta, \gamma$ and $\delta$ (the greatest change in the quantities $C_{x}, L_{2}, K_{1}$ and $R_{2}$ because of the compressibility of water in the case of a disc) was $12.7,22.9,32.2$ and $2.9 \%$, respectively, in the range $Q \in[0.15,1], M_{c} \in[0,1]$
Putting $L=L_{2} /\left(2 R_{2}\right), L^{0}=L_{2}^{0} /\left(2 R_{2}^{0}\right), \sigma=\beta / \delta$, we write by analogy with (6.1), the equality $L=\sigma L^{0}$ ( $L$ is the length of the cavern, $\left.\sigma=\sigma\left(M_{c}, Q\right)\right)$. It follows from the approximation relationships (6.1) that the inequalities $\partial \sigma / \partial M_{c}>0, \partial \sigma / \partial Q<0$ hold in the range $Q \in[0.15,1], M_{c} \in[0,1]$. According to the last of these inequalities, the effect of compressibility on the elongation of the cavern increases as $Q$ decreases. Meanwhile, an analysis of the solution of the problem in a linearized formulation leads to a contradictory assertion $[9,10]$. This apparent contradiction is explained by the difference in the domains of applicability of the results: the results obtained in $[9,10]$, using the assumptions of the gas dynamics of a thin body, are valid for small $Q$ numbers (the smaller the value of $Q$, the more accurate are the equations) and for $M_{c}$ numbers which are sufficiently far from unity.
The dependence of the elongation $L$ of the cavern behind the disc on the number $Q$ for the values $M_{c}=0,0.6$ and 1 is shown in Fig. 7 (curves 1-3 respectively). In order to construct curves 1 and 2 in the interval $0.075 \leqslant Q \leqslant 0.15$, the left boundary of which is marked by means of a broken line, the results of the solution of four additional versions of the problem were used. These versions correspond to the values $Q=0.075,0.1$ and $M_{c}=0,0.6$ (it is not possible to obtain a solution for these values of $Q$ when $M_{c}=1$ ). As $Q$ decreases in the range $0.075 \leqslant Q \leqslant 0.1$, the ratio of the ordinates of curves 2 and 1 , which is equal to $\sigma(0.6, Q)$, approaches unity. This confirms the non-contradictory nature of the results of the linear and non-linear theories. At the same time, there are no reasons to expect that the ratio of the ordinate of curves 1 and 3 will tend to unity when $Q \rightarrow 0$ when they are extended into the region of small $Q$ values.


Fig. 7.
7. Further calculations were carried out on 36 versions of the governing parameters corresponding to the values $k=7.15 ; Q=0.15 ; 0.2 ; 0.4 ; 1 ; M_{c}^{2}=0.5 ; 0.75 ; 1 ; \theta_{0}=2 \pi / 3,5 \pi / 6, \pi$. It was established that, in the calculation of the parameters $L_{1}, L_{2}, K_{1}, R_{2}$ using the approximation formulae

$$
\begin{equation*}
L_{1}=\beta L_{1}^{0}, \quad L_{2}=\beta L_{2}^{0} . \quad K_{1}=\gamma K_{1}^{0}, \quad R_{2}=\delta R_{2}^{0} \tag{7.1}
\end{equation*}
$$

where $L_{1}^{0}, L_{2}^{0}, K_{1}^{0}, R_{2}^{0}$ are functions of $Q$ and $\theta_{0}$ defined by formulae (5.1) and Table 2 and $\beta, \gamma$ and $\delta$ are functions of $Q$ and $M_{c}$ defined by formulae (6.1) and Table 3, the resulting error does not exceed $2 \%$ for $K_{1}$ and $1.5 \%$ for $L_{1}, L_{2}$ and $R_{2}$. Formulae (7.1) are therefore suitable for use in the range $Q \in[0.15,1]$, $M_{c} \in[0,1], \theta_{0} \in[\pi / 2, \pi]$.
To calculate $C_{x}$ over the same range, it is better not to use a formula of the form (7.1) but the approximation relationship

$$
C_{x}=C_{x}^{\prime}+4\left(C_{x}^{\prime \prime}-C_{x}^{\prime}\right)\left(1-\theta_{0} / \pi\right)^{2}
$$

where $C_{x}^{\prime}$ is the exact value of $C_{x}$ when $\theta_{0}=\pi$ (see (4.6)) and $C_{x}^{\prime \prime}$ is the value of $C_{x}$ when $\theta_{0}=\pi / 2$ calculated using the first of formulac (6.1). The resulting error in this case does not exceed $0.5 \%$.

It is not possible to propose a convenient approximation formula for calculating the values of $R_{1}$ when $M_{c} \neq 0$. However, it may be stated that, as $M_{c}$ increases from zero to unity, the magnitude of $R_{1}$ decreases, but by not more than $1 \%$.

It follows from the determination of the cavitation number $Q$ that

$$
\begin{equation*}
M_{a}^{2}=2\left(p_{a}-p_{v}\right) /\left(\rho_{a} a_{a}^{2} Q\right) \tag{7.2}
\end{equation*}
$$

holds in the case of steam cavitation, where $p_{v}$ is the pressure of the saturated vapours at the specified temperature and $M_{a}^{\prime}$ and $a_{a}$ are the values of the number $M$ and the velocity of sound $a$ in the unperturbed flow. By using the well-known values of $p_{v}, \rho_{a}, a_{a} c$ and (7.2), it can be readily shown that, under normal conditions when the pressure of the approach stream $p_{a}$ is of the order of 1 atmosphere, negligibly small values of $M_{a}$ and $M_{c}$ correspond to the value $Q=0.15$. As $p_{a}$ increases at the fixed value of $Q=0.15$, the values of $M_{c}$ and $M_{c}$ become larger but it is only at a value of $p_{a}$ of the order of 900 atmospheres that $M_{c}$ attains a value of unity. From what has been said, it has to be acknowledged that (6.1) and (7.1) are of greater theoretical than practical interest.

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